Intake reverse motor?

Score piece (eject manipulator)

Run manipulator to grab/choke up on piece (while held)

Score mid position

Score high position

Elevator bottom position

Score low position

(hold) Manual elevator/ wrist enable

Manual elevator (X-axis)

Manual wrist  
(X-axis)

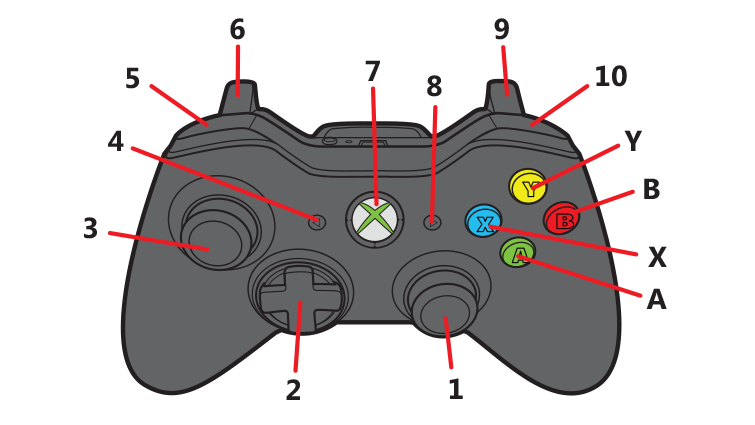
Up: Prep for get cone

Down: Prep for get cube

Left:

Right: Elevator loading station

Stop motors



Score piece

Move to

Scoring position

Intake out

Intake in